

Simulating electromagnetic instabilities in tokamaks with gyrokinetic particle-in-cell code **GTS** *

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Abstract

- Recently, the numerical scheme presented in [1] enabled explicit gyrokinetic simulations of low-frequency electromagnetic instabilities in tokamaks at experimentally relevant values of plasma beta.
- This scheme resolved the long-standing "cancelation problem" that previously hindered gyrokinetic particle-in-cell code simulations of electromagnetic phenomena with inherently small parallel electric fields.
- Moreover, the scheme did not employ approximations that eliminate critical tearing-type instabilities.
- Here, we report on the implementation of this numerical scheme in the global gyrokinetic particle-in-cell code GTS.
- Additionally, we present a comprehensive set of verification simulations of numerous electromagnetic instabilities: kinetic ballooning mode (KBM), the internal kink mode, the tearing mode, the micro-tearing mode (MTM) and toroidal alfvén eigenmode (TAE) destabilized by energetic ions, which are all instrumental in understanding tokamak physics.
- We also showcase the preliminary nonlinear simulations of the kinetic ballooning instability and (2,1) island formation due to the tearing mode instability.

[1] A. Mishchenko, M. Cole, R. Kleiber, A. Konies, Phys. Plasmas 21 (2014) 052113.

Gyrokinetic Equations solved in PIC codes

- Particle drift equations for $(\mathbf{R}, v_{\parallel}, \mu)$ are

$$\dot{\mathbf{R}} = \frac{1}{B_{\parallel}^*} \left[v_{\parallel} \mathbf{B}^* + \frac{c}{q} \mathbf{b} \times \nabla H \right], \quad m \dot{v}_{\parallel} = -\frac{1}{B_{\parallel}^*} \mathbf{B}^* \cdot \nabla H - \frac{q}{c} \frac{\partial \bar{A}_{\parallel}}{\partial t}, \quad \dot{\mu} = 0, \quad (1)$$

where $\mathbf{B}^* = \nabla \times \mathbf{A}^*$, $B_{\parallel}^* = \mathbf{b} \cdot \mathbf{B}^*$, $\mathbf{A}^* = \mathbf{A}_0 + (A_{\parallel} + \frac{mc}{q} v_{\parallel}) \mathbf{b}$ and $H = mv_{\parallel}^2/2 + q\phi$.

- In δf simulations the particle weight is defined as $w = \delta f/f$ with $\delta f = f - f_0$. and Vlasov equation with collision operator $C[w]$ reads as

$$\frac{dw}{dt} = -(1-w) \frac{d}{dt} \ln f_0 + C[w]. \quad (2)$$

- The gyrokinetic Poisson for ϕ is given by

$$-\nabla_{\perp} \cdot \frac{n_0 c}{B \Omega_i} \nabla_{\perp} \phi = \delta \bar{n}_i - \delta n_e, \quad (3)$$

and Ampere's law for electromagnetic potential A_{\parallel}

$$\nabla_{\perp}^2 A_{\parallel} = -\frac{4\pi}{c} \delta j = -\frac{4\pi}{c} (\delta j_e + \delta \bar{j}_i). \quad (4)$$

Illustration of Cancellation Problem

- To remove time derivative $\frac{\partial A_{\parallel}}{\partial t}$ in Eq.(1) introduce $p_{\parallel} = v_{\parallel} + \frac{q}{mc}A_{\parallel}$. which modifies Ampere's law

$$k_{\perp}^2 A_{\parallel} + \frac{1}{\lambda_e^2} A_{\parallel} = -\frac{4\pi}{c} \delta j_p.$$

- The skin-term will be incompletely canceled numerically by adiabatic contribution from δj_p

$$k_{\perp}^2 \left(1 + \frac{\epsilon}{\lambda_e^2 k_{\perp}^2} \right) A_{\parallel} = S_1 A_h.$$

- Here $A_h = -i(c/\omega)E_{\parallel}$. From Poisson equation $\phi = \frac{\omega}{k_{\parallel}} S_2 A_h / (\rho_i k_{\perp})^2$, and

$$A_{\parallel} = A_h + \frac{k_{\parallel}}{\omega} \phi = A_h + \frac{S_2}{\rho_i^2 k_{\perp}^2} A_h \approx \frac{S_2}{\rho_i^2 k_{\perp}^2} A_h$$

- The dispersion relation for shear-Alfven waves then has error term $\epsilon / (\lambda_e k_{\perp})^2$

$$\omega^2 = v_A^2 k_{\parallel}^2 \left[1 + \epsilon \frac{1}{\lambda_e^2 k_{\perp}^2} \right].$$

- To get correct alfven wave dispersion for $k_{\perp} \sim 1/a$ we need

$$\epsilon \sim \frac{1}{\sqrt{N}} \ll (\lambda_e/a)^2.$$

Another way of removing time derivative from equation of motion

- Switching to a new velocity variable v_h defined as

$$v_h = v_{\parallel} + \frac{q}{mc} A_h, \quad (5)$$

where field quantities A_h and A_s are defined as

$$A_h = -c \int_{t_0}^t E_{\parallel} dt, \quad A_s = -c \int_{t_0}^t \mathbf{b}_0 \cdot \nabla \phi dt + A_{\parallel}(t_0), \quad (6)$$

with $A_{\parallel}(t) = A_h(t) + A_s(t)$, the guiding center equations for v_h become

$$m\dot{v}_h - \frac{q}{c} \dot{\mathbf{R}} \cdot \nabla A_h = -\frac{1}{B_{\parallel}^*} \mathbf{B}^* \cdot \nabla H + q\mathbf{b} \cdot \nabla \phi. \quad (7)$$

- Time derivative is eliminated and the r.h.s contains only magnetic drift and mirror terms.
- Because $A_h/A_{\parallel} \sim \rho_i^2 k_{\perp}^2$ the error is reduced by factor $\rho_i^2 k_{\perp}^2$

$$\omega^2 = v_A^2 k_{\parallel}^2 \left[1 + \epsilon \frac{\rho_i^2}{\lambda_e^2} \right].$$

- To get correct alfvén wave frequency we need

$$\epsilon \sim \frac{1}{\sqrt{N}} \ll (\lambda_e/\rho_i)^2 = \frac{1}{\beta m_i/m_e}.$$

Pullback scheme to reduce error

- To reduce error further do periodic shifts of t_0 in definition of A_h .
- After each shift during the simulation at some time moment t_1 , A_s is reset to be

$$A_s^{new}(t_1) = A_s^{old}(t_1) + A_h^{old}(t_1) = A_{\parallel}(t_1) \quad (8)$$

and A_h is reset to zero $A_h^{new} = 0$ by setting $t_0 = t_1$ in Eq. (6).

- The parallel particle velocity $v_{\parallel}(t_1)$ at time t_1 is different from velocity $v_h^{old}(t_1)$ at the same time

$$v_{\parallel}(t_1) = v_h^{old}(t_1) - \frac{q}{mc} A_h^{old}(t_1) \quad (9)$$

$$= v_h^{new}(t_1) - \frac{q}{mc} A_h^{new}(t_1) = v_h^{new}(t_1). \quad (10)$$

- The value of distribution function carried by the particle is not changed $f^{new}(t_1) = f^{old}(t_1)$ while the value of f_0 at the particle location in the phase space is changed as

$$f_0(v_h^{new}) = f_0(v_{\parallel}) = f_0(v_h^{old} - \frac{q}{mc} A_h^{old}). \quad (11)$$

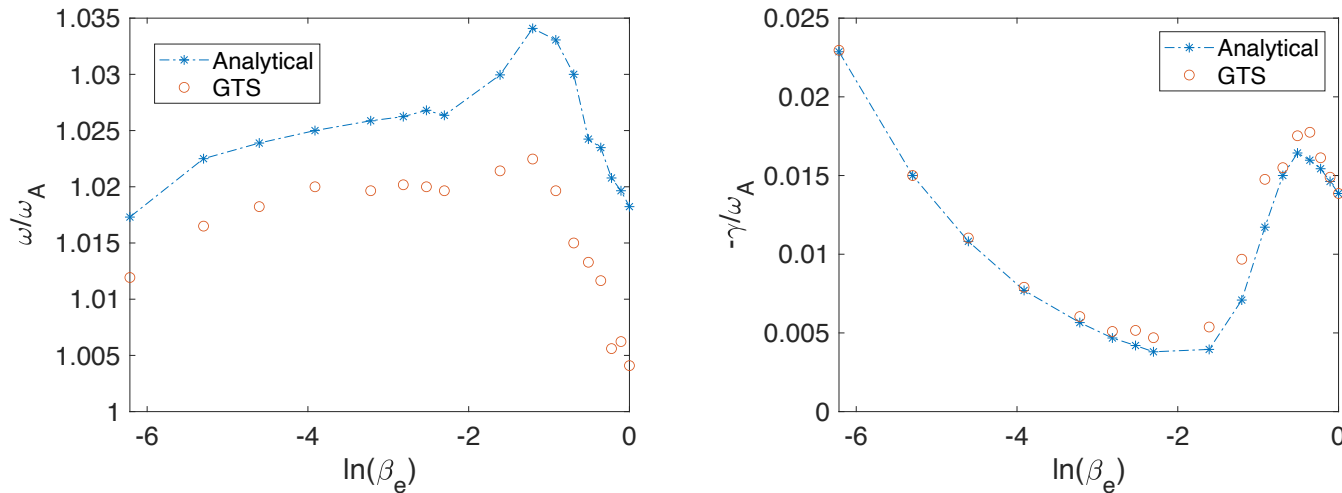
- The weights are changed according to $w = 1 - f_0/f$

Simulation of (2,2) Alfvén mode

- Almost cylindrical plasma with $R/a = 100$, $a/\rho_i = 25$, $q = 2$ and $T_i = T_e$.
- Initial mode profile is an eigenfunction of $-\nabla^2$ with a smallest eigenvalue k_{\perp}^2 for a given $m = 2$.
- Solve analytical dispersion relation for ω

$$k_{\perp}^2 \rho_i^2 + \left(1 - \frac{\omega^2}{\omega_A^2}\right) [(1 + X_e) + (1 + X_i)] = 0 \quad (12)$$

- Here $\omega_A = v_A k_{\parallel}$, $X_{e,i} = \zeta_{e,i} Z(\zeta_{e,i})$ and $\zeta_{e,i} = \omega / (v_{e,i}^{th} k_{\parallel})$.



Removing errors when gradients are present

- Linearized Vlasov equation can be written symbolically as

$$(\omega - kv - \omega_d)w = \omega_d\phi - \omega^*(\phi - vA) + \left(\phi - \frac{\omega}{k}A\right)kv.$$

- Here $\frac{q}{T}\phi \rightarrow \phi$ and $\frac{q}{cT}A_{\parallel} \rightarrow A$. Writing $A = \frac{k}{\omega}\phi + A_h$ it can be simplified to

$$(\omega - kv - \omega_d) \left(w + \frac{\omega^*}{\omega}\phi \right) = \left(1 - \frac{\omega^*}{\omega} \right) (\omega_d\phi - \omega v A_h).$$

- R.H.S contains only small terms in MHD limit.
- Large parts $\frac{\omega^*}{\omega}\phi$ contribute to Poisson equation only a small term $\delta n/n_0 = k_{\perp}^2 \rho_i^2 \frac{\omega^*}{\omega} \phi$ due to cancellations of contribution from electrons and ions.
- If not canceled correctly, large error term is introduced $\delta n^{err}/n_0 \sim \epsilon \frac{\omega^*}{\omega} \phi$ and

$$\omega^2 = \omega_{DA}^2 \left[1 + \epsilon \left(\frac{\omega^*}{\omega_{DA}} \right) \frac{1}{\rho_i^2 k_{\perp}^2} \right].$$

MHD equations in gyrokinetic codes

- By taking time derivative of gyro-kinetic Poisson equation, using linearized drift-kinetic Vlasov equations and Ampere's law to eliminate parallel current and setting $E_{\parallel} = -\partial_{\parallel}\phi - (1/c)\partial_t A_{\parallel} = 0$ we get

$$\nabla_{\perp} \cdot \frac{\omega^2}{v_A^2} \nabla_{\perp} \phi + \partial_{\parallel} \nabla_{\perp}^2 \partial_{\parallel} \phi - \frac{\mathbf{b} \times \nabla \partial_{\parallel} \phi \cdot \nabla}{B} \left(\frac{4\pi}{c} j_{\parallel 0} \right) = -\frac{4\pi\omega}{c^2} \sum_s q_s n_s \langle \omega_{ds} w \rangle =$$

$$\frac{4\pi}{c^2} \sum_s \frac{q_s^2 n_s \langle \omega_{ds} \omega_s^* \rangle}{T_s} \phi - i \frac{4\pi^2}{c^2} \sum_s \frac{q_s^2 n_s}{T_s} \langle \omega_{ds} \delta(\omega - k_{\parallel} v) (\omega - \omega_s^*) \omega_{ds} \rangle \phi.$$

- Here $\langle \rangle$ means averaging over Maxwellian velocity distribution function.
- First two terms represent dispersion equation for shear-alfven wave.
- Third term provides free energy for tearing and kink modes.
- First term on r.h.s. is a curvature drive for ballooning instability and kink mode in toroidal geometry.
- The last terms is responsible for destabilization of TEA mode by energetic particles.

"Invariant Embedding" Method Cylindrical Eigenmode code

- For set of linear equations for $\mathbf{u} = (u_1, u_2)$

$$\frac{d^2}{dr^2}\mathbf{u} = \hat{A}(r, \omega)\mathbf{u} + \hat{B}(r, \omega)\frac{d}{dr}\mathbf{u}.$$

- Matrices $\hat{A}(r, \omega)$ and $\hat{B}(r, \omega)$ are found by solving Vlasov equation.
- Introduce matrix $\hat{R}(r, \omega)$ as

$$\mathbf{u} = \hat{R}(r, \omega)\frac{d}{dr}\mathbf{u}.$$

- Equation for $\hat{R}(r, \omega)$ is the matrix Riccati equation

$$\frac{d}{dr}\hat{R}(r, \omega) = 1 - \hat{R}(r, \omega)\hat{B}(r, \omega) - \hat{R}(r, \omega)\hat{A}(r, \omega)\hat{R}(r, \omega).$$

- The boundary conditions $\mathbf{u}(a) = 0$ and $\mathbf{u}(b) = 0$ set boundary conditions for $\hat{R}(r, \omega)$

$$\hat{R}(a, \omega) = 0, \text{ and } \hat{R}(b, \omega) = 0.$$

- Integrate Riccati equation on the interval $a < r < r_0$ to obtain $\hat{R}^-(r_0, \omega)$ and on the interval $r_0 < r < b$ to obtain $\hat{R}^+(r_0, \omega)$.

"Invariant Embedding Method" Cylindrical Eigenmode code, cont'd

- The eigenvalue equation is

$$\det[\hat{R}^+(r_0, \omega) - \hat{R}^-(r_0, \omega)] = 0.$$

- The method only searches in 2-d complex- ω plane, instead of 4-d $[\omega, u'_2(a)/u'_1(a)]$ space of original system.
- After ω is found, eigenfunctions are found by solving first order equations for $\mathbf{v} = d\mathbf{u}/dr$

$$\frac{d}{dr}\mathbf{v} = \hat{A}(r, \omega)\hat{R}(r, \omega)\mathbf{v} + \hat{B}(r, \omega)\mathbf{v}.$$

- With boundary conditions at rational surface $r = r_0$ for $\mathbf{v} = (v_1, v_2) = (u'_1(r_0), u'_2(r_0))$ are

$$v_1(r_0) = 1, \quad \text{and} \quad (R_{12}^+ - R_{12}^-)v_2(r_0) + (R_{11}^+ - R_{11}^-) = 0.$$

- Next, use definition of \hat{R} to find \mathbf{u} : $\mathbf{u} = \hat{R}(r, \omega)\mathbf{v}$.

Drift-Tearing Mode Properties

- Ampere law inside the current layer

$$-i\omega = \frac{1}{j_{\parallel}} \frac{\partial j_{\parallel}}{\partial t} = \frac{\partial_r^2 E_{\parallel}}{4\pi j_{\parallel}/c^2} = \frac{c^2}{4\pi\delta} \left[\frac{\partial_r E_{\parallel}|_{-\delta/2}^{\delta/2}}{E_{\parallel}} \right] \left(\frac{E_{\parallel}}{j} \right) = \left[\frac{\Delta' \delta_e^2}{\delta} \right] \left(\frac{-eE_{\parallel}/m_e}{v_{\parallel}^e} \right).$$

- where $\Delta' = \partial_r E_{\parallel}|_{-\delta/2}^{\delta/2}/E_{\parallel} = \partial_r A|_{-\delta/2}^{\delta/2}/A$ is obtained from equilibrium equation outside the layer

$$\nabla_{\perp}^2 A = \frac{4\pi j'_0(r) k_{\theta}}{cB} \frac{k_{\theta}}{k_{\parallel}} A.$$

- Using electrons moment equation

$$(\nu - i\omega)v_{\parallel}^e = \left(1 - \frac{\omega^*}{\omega} \right) \frac{-eE_{\parallel}}{m_e}$$

- We get relation between the width of the current layer and mode frequency.

$$\frac{\delta}{\Delta' \delta_e^2} = \frac{\omega + i\nu}{\omega - \omega^*}.$$

Drift-Tearing Mode Properties

- The parallel electron current with frequency ω can only be driven inside the narrow region of width δ such that (for $\delta < \rho_i$)

$$\omega(\omega + i\nu) \approx [v_{te}k_{\parallel}(\delta)]^2 = [v_{te}k'_{\parallel}\delta]^2$$

- Combining, we obtain the dispersion relation for drift-tearing mode

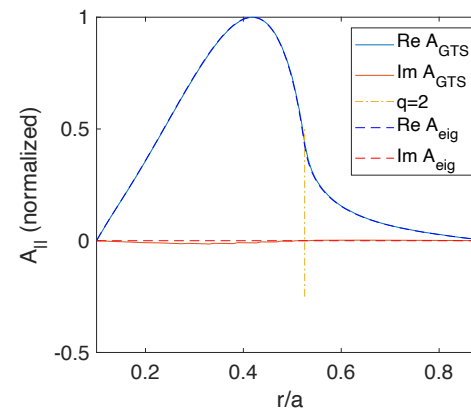
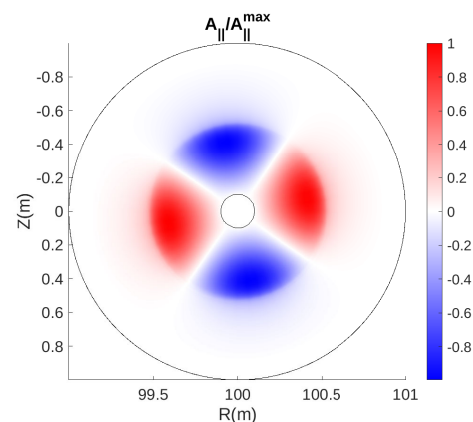
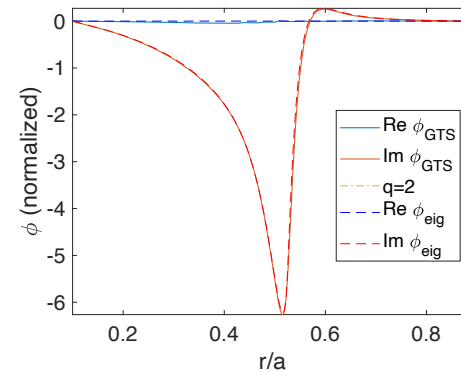
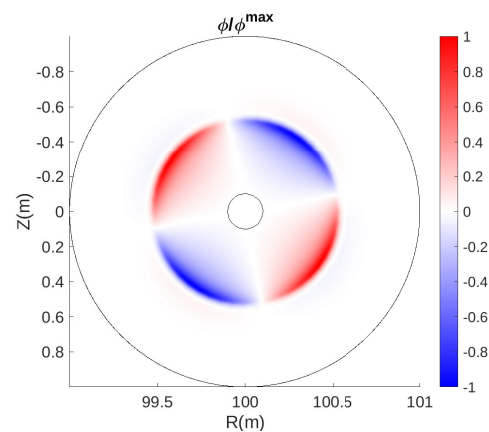
$$(\omega - \omega^*)^2 = -\gamma_c^2 \left(1 + \frac{i\nu}{\omega}\right)$$

where $\gamma_c \equiv v_{te}k'_{\parallel}\Delta'\delta_e^2$

- For $\nu = 0$ and $\omega^* = 0$, $\omega = i\gamma_c$, $\delta = \delta_c \equiv \Delta'\delta_e^2$.
- For $\nu = 0$ and $\omega^* \gg \gamma_c$, $\omega = \omega^* + i\gamma_c$, $\delta = \delta_c \left(\frac{\omega^*}{\gamma_c}\right)$.
- For $\nu \gg \gamma_c$ and $\omega^* = 0$, $\omega = i\gamma_c \left(\frac{\nu}{\gamma_c}\right)^{1/3}$, $\delta = \delta_c \left(\frac{\nu}{\gamma_c}\right)^{2/3}$.
- For $\omega^* \neq 0$ and $\nu \gg \omega^*$, $\omega = \omega^* + i\gamma_c \left(\frac{\nu}{\omega^*}\right)^{1/2}$, $\delta = \delta_c \frac{(\nu\omega^*)^{1/2}}{\gamma_c}$.

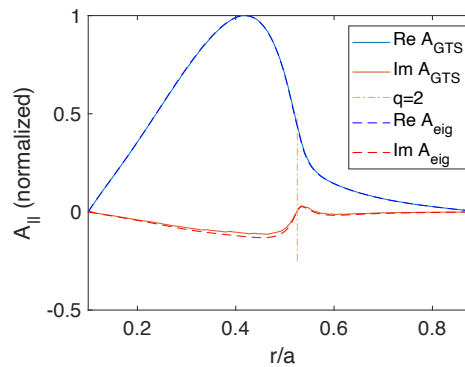
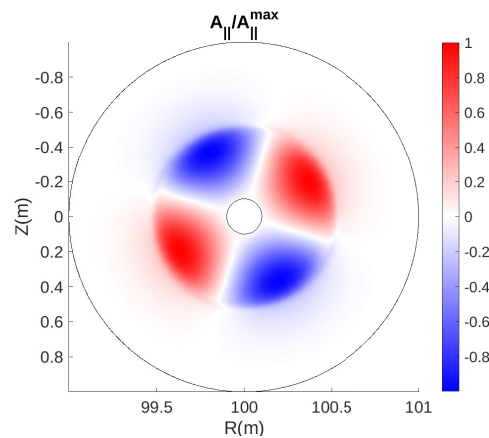
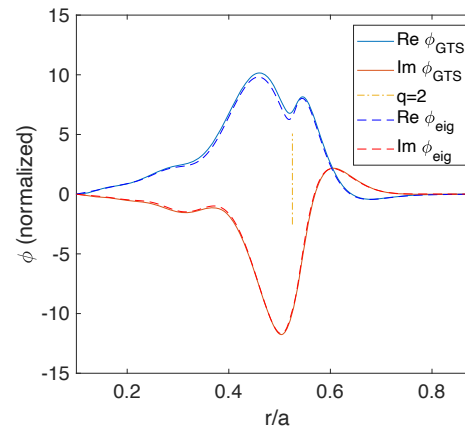
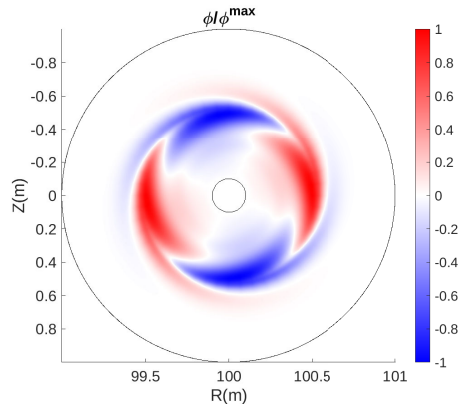
Simulation of (2,1) Tearing mode

- $a/\rho_i = 50$, $R/a = 100$, $q(r) = 1.725/(1 - 0.5r^2/a^2)$, $\beta_e = 0.001$, $R/L = 0$, $\nu = 0$.
- $\omega_{GTS} = 0.113c_s/R$ while $\omega_{eig} = 0.115c_s/R$.



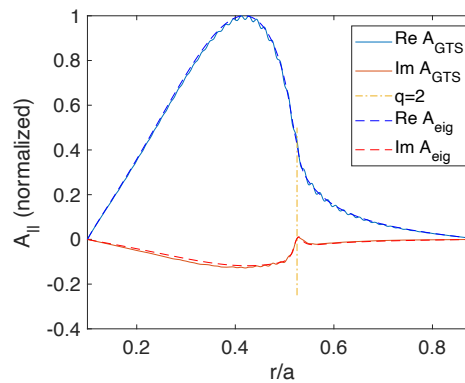
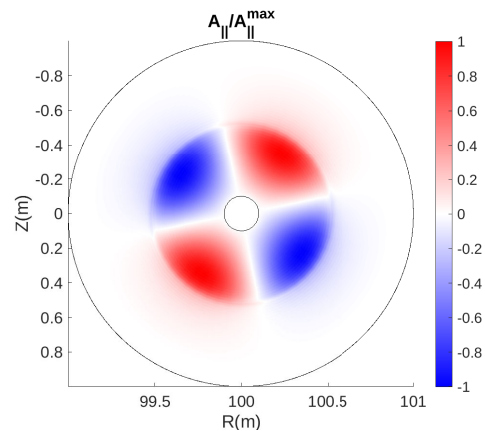
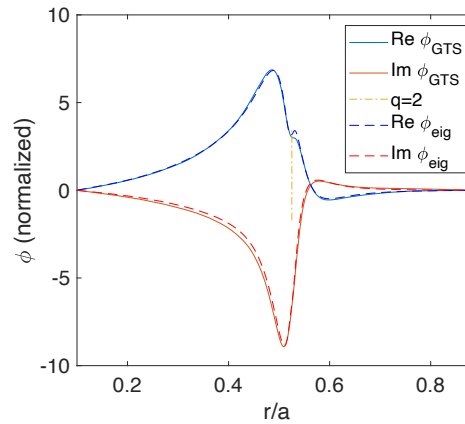
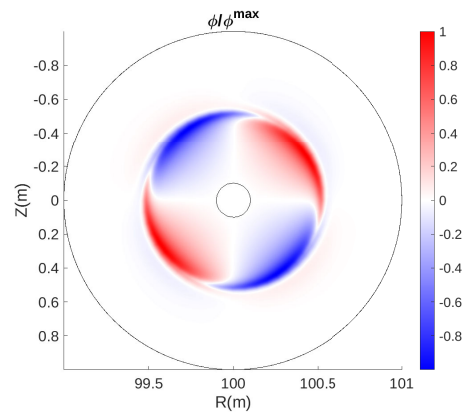
Simulation of (2,1) Drift-tearing mode, $R/L_n = 5$

- $a/\rho_i = 50$, $R/a = 100$, $q(r) = 1.725/(1 - 0.5r^2/a^2)$, $\beta_e = 0.001$, $R/L_T = 0$, $R/L_n = 5$, $\nu = 0$.
- $\omega_{GTS} = (-0.37 + i0.13)c_s/R$ while $\omega_{eig} = (-0.36 + i0.13)c_s/R$.



Simulation of (2,1) Drift-tearing mode, $R/L_{Te} = 5$

- $a/\rho_i = 50$, $R/a = 100$, $q(r) = 1.725/(1 - 0.5r^2/a^2)$, $\beta_e = 0.001$, $R/L_{Te} = 5$, $R/L_n = 0$, $\nu = 0$.
- $\omega_{GTS} = (-0.24 + i0.10)c_s/R$ while $\omega_{eig} = (-0.23 + i0.10)c_s/R$.



Micro-tearing Mode

- $\Delta' > 0$ is satisfied only for small mode numbers (e.g., $m = 2$ or 3).
- For higher mode numbers, a tearing mode can also be destabilized with a much larger growth rate $\gamma \gg \gamma_c$ due to the dependence of the electron collision frequency on velocity

$$\left\langle \left(\frac{v}{v_{te}} \right) \frac{[\omega - \omega^*(v)]}{[1 + i\nu(v)/\omega]^{1/2}} \right\rangle_v = i\gamma_c$$

or

$$\left(1 - \frac{\omega_n^*}{\omega} \right) f_1 \left(\frac{\bar{\nu}}{\omega} \right) - \frac{\omega_{Te}^*}{2\omega} f_2 \left(\frac{\bar{\nu}}{\omega} \right) = i \frac{\gamma_c}{\omega} \approx 0$$

where $\bar{\nu}$ is characteristic value of collision frequency.

- If $\omega_{Te}^* = 0$, $\omega \approx \omega_n^*$ and the mode is stable (if $\gamma_c/\omega_n^* \ll 1$ is neglected)
- If $\omega_{Te}^* \neq 0$ the mode is unstable. For example for $\omega_n^* = 0$

$$\frac{\omega}{\omega_{Te}^*} = F \left(\frac{\bar{\nu}}{\omega_{Te}^*} \right).$$

Implementation of collisions in GTS and eigenmode code

- $C[\delta f_e]$ is the electron pitch-angle scattering collision operator

$$C[\delta f_e] = \frac{\nu(v)}{2} \frac{\partial}{\partial \xi} (1 - \xi^2) \frac{\partial}{\partial \xi} \delta f_e,$$

where $\xi = v_{\parallel}/v$ has been implemented in the code using Langeven equation

$$v'_{\parallel} = v_{\parallel} [1 - \nu(v)dt(1 + \alpha^2)/2] - v_{\perp} \alpha \sqrt{\nu(v)dt},$$

where α takes randomly on values ± 1 and

$$\nu(v) = \bar{\nu} \left(\frac{v_{te}}{v} \right)^3$$

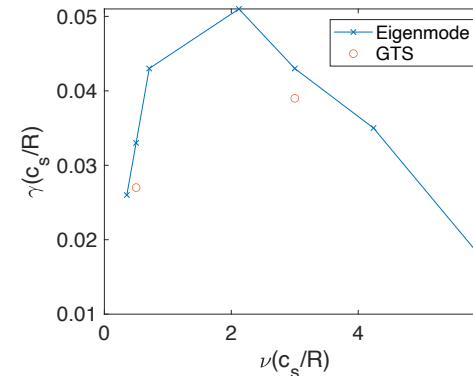
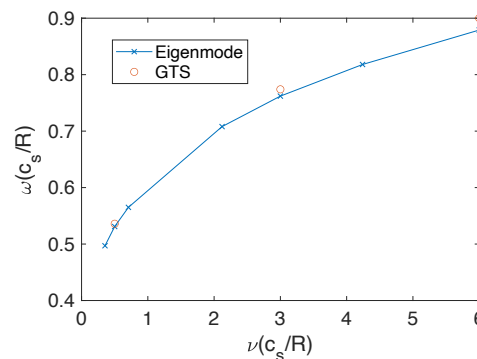
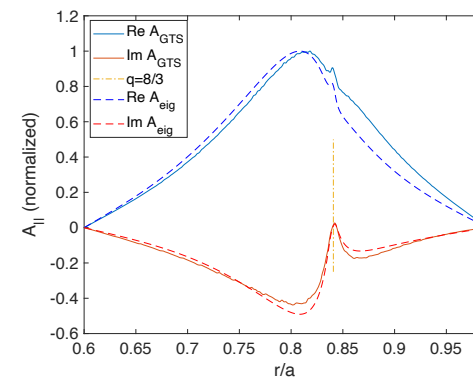
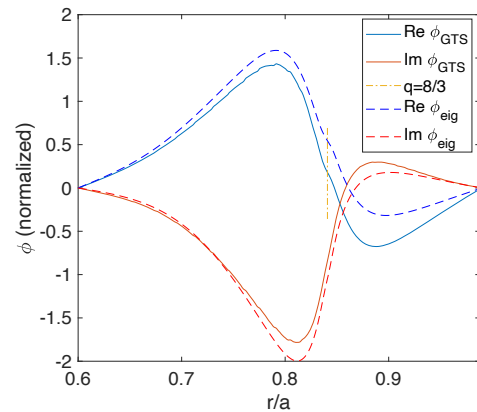
- Matrices $\hat{A}(r, \omega)$ and $\hat{B}(r, \omega)$ are found by solving collisional Vlasov equation and solution for electron current and density can be expressed exactly using "continued" fractions, i.e.,

$$A_{12} = \int v^n dv F_{e0}(v) \left[a_0 + \frac{b_0}{a_1 + \frac{b_1}{a_2 + \frac{b_2}{a_3 + \dots}}} \right],$$

- with a_n and b_n being functions of $k_{\parallel}v/\omega$, ω^*/ω , and $\nu(v)/\omega$ and index n , and converge very fast for $\bar{\nu}/\omega > 0.1$.

Simulation of (8,3) Micro-tearing mode

- $a/\rho_i = 25$, $R/a = 100$, $q(r) = 1.725/(1 - 0.5r^2/a^2)$, $\beta_e = 0.06$, $T_i = T_e$,
 $R/L_n = 0$, $R/L_{Te} = 2$, $R/L_{Ti} = 0$, $\nu = \bar{\nu}/(v/v_{th})^3$



[1] "Electron temperature gradient driven microtearing mode", N. T. Gladd et. al., Physics of Fluids **23**, 1182 (1980).

(1,1) Kink mode

- In tokamaks with $R/a \gg 1$ and circular flux-surfaces and no Shafranov shift MHD equations for $\xi = \phi/r$ with $\xi = \sum_m \exp(im\theta)\xi_m$ take form

$$\frac{d}{dr}r^3 \left(n_{(1,1)\parallel}^2 + \frac{\gamma^2}{\omega_A^2} \right) \frac{d}{dr}\xi_{m=1} = R \frac{d}{dr}\beta' r^2 \xi_{m=2}$$

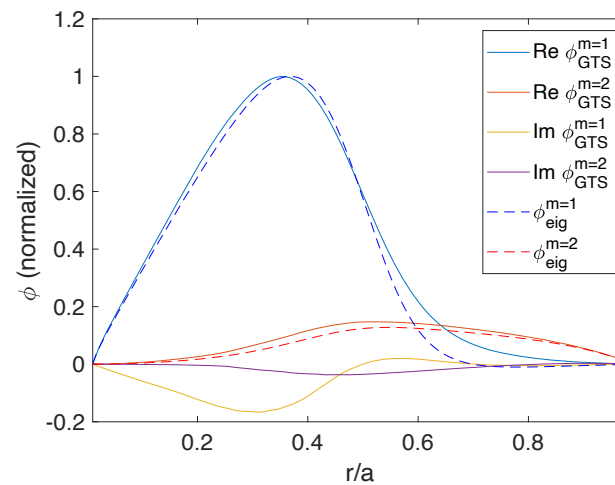
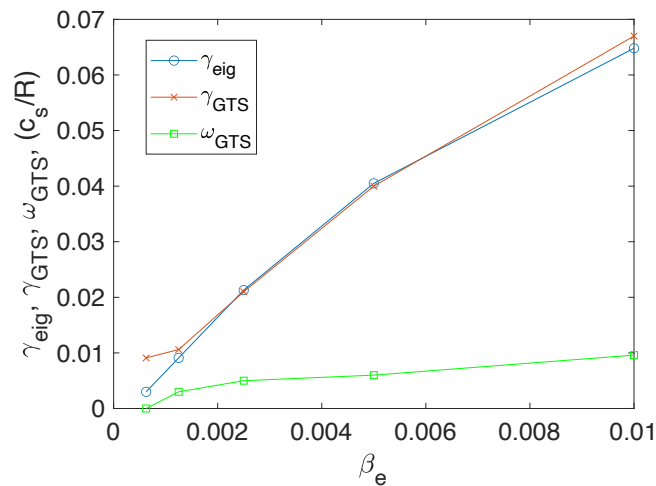
$$\frac{d}{dr}r^3 \left(n_{(1,2)\parallel}^2 + \frac{\gamma^2}{\omega_A^2} \right) \frac{d}{dr}\xi_{m=2} - 3 \left(n_{(1,2)\parallel}^2 + \frac{\gamma^2}{\omega_A^2} \right) \xi_{m=2} = -R \frac{r^3}{2} \frac{d}{dr} \frac{\beta'}{r} \xi_{m=1}$$

here $n_{(n,m)\parallel} = n - m/q(r)$

- Terms on the r.h.s come from pressure-curvature coupling.
- The strength of the coupling scales as $\beta \frac{R}{L_p}$.
- For $\beta R/L_p \ll 1$, $\xi_{m=1} \approx \text{const}$ all the way to rational surface $q = 1$ where coupling becomes significant, since $n_{(1,1)\parallel} \approx 0$.
- Coupling removes the singularity near rational surface and localizes the mode inside $q = 1$ surface.

Simulation of (1,1) Kink mode

- $a = 1m$, $R/a = 10$, $B = 1T$, $a/\rho_i = 180$, $q(r) = 0.8(1 + r^2/a^2)$.
- $n(r) = n_0 \exp \left[-0.6 \tanh \left(\frac{r/a - 0.5}{0.2} \right) \right]$.



[1] "Pullback scheme implementation in ORB5", A. Mishchenko et. al., Computer Phys. Comm., **238**, 194-202 (2019).

Toroidal Alfvénic Eigenmode

- MHD equations for TAE in the limit $R/a \gg 1$ and $\beta R/a \ll 1$ are

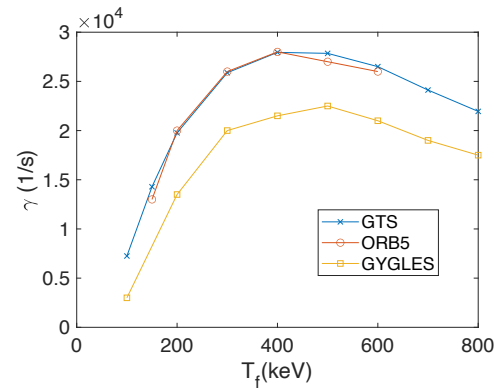
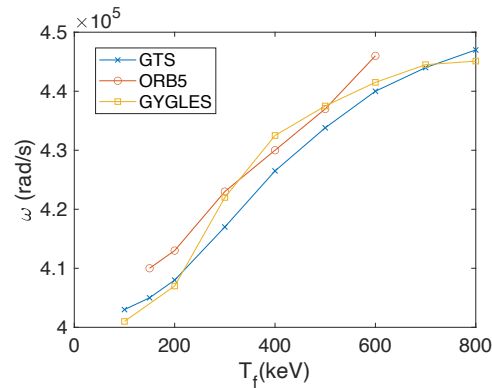
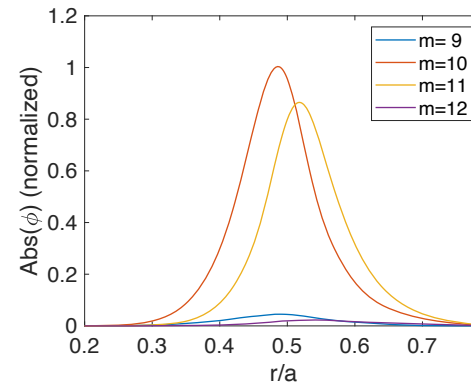
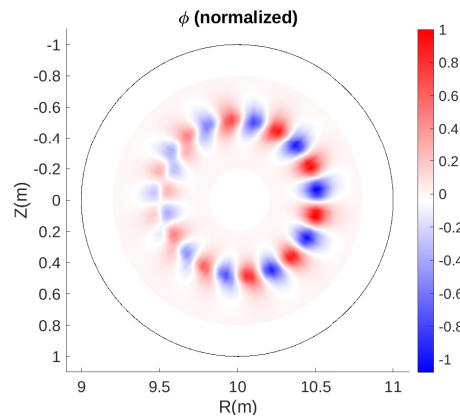
$$\nabla_{\perp} \cdot \frac{\omega^2}{\omega_A^2} \nabla_{\perp} \phi - n_{\parallel} \nabla_{\perp}^2 n_{\parallel} \phi = 0,$$

where $n_{\parallel} = n - m/q(r)$.

- Near a surface where $n_{m\parallel} = -n_{m+1\parallel}$ the modes with m and $m + 1$ are resonantly coupled due to a weak dependence of $\omega_A \sim B$ on poloidal angle θ .
- This coupling removes the degeneracy at the crossing point producing a frequency gap.
- It also produces an effective potential well for the mode which confines it near the crossing point producing a global TAE mode.
- If energetic particles are present near phase velocity of the wave, the wave can become unstable.
- The mode is damped by electrons and background ions and by interaction with alfvénic continuum.

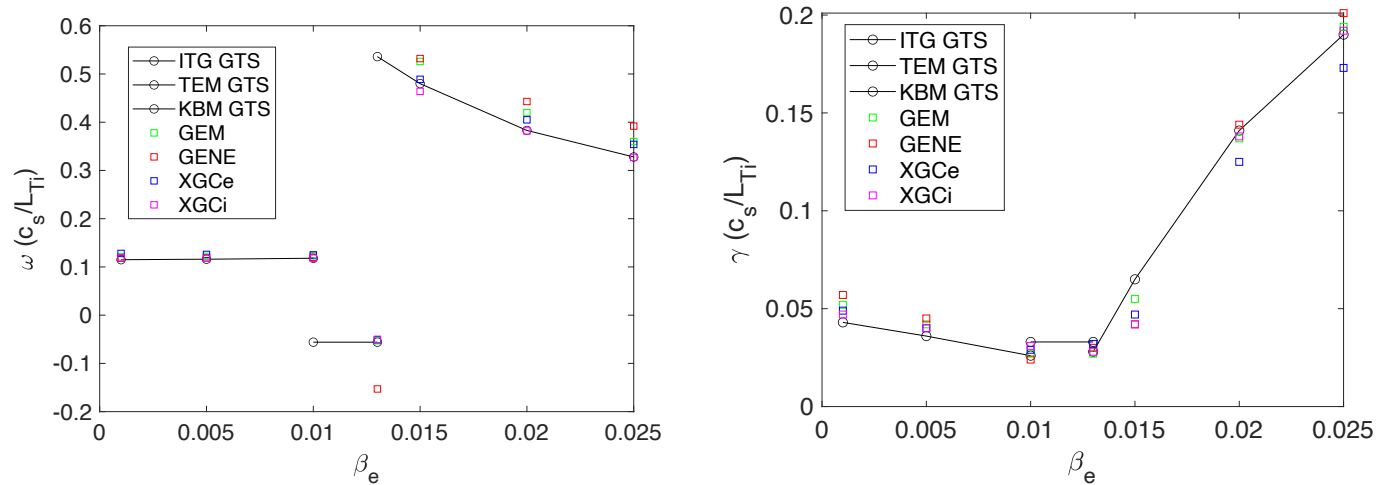
Simulation of n=6 TAE mode

- Hydrogen plasma with $a = 1m, R = 10m, B = 3T, q(r) = 1.71 + 0.16(r/a)^2, n = 2 \cdot 10^{19}m^{-3}, T_i = T_e = 1keV$
- Hot species: deuterium with Maxwellian velocity distribution with $100keV \leq T_h \leq 800keV$
- $n_h(r) = n_{0h} \exp \left[-\frac{2}{3} \tanh \left(\frac{r/a - 0.5}{0.2} \right) \right], n_{0h} = 0.75 \cdot 10^{17}m^{-3}$



Simulation of ITG-TEM-KBM transition

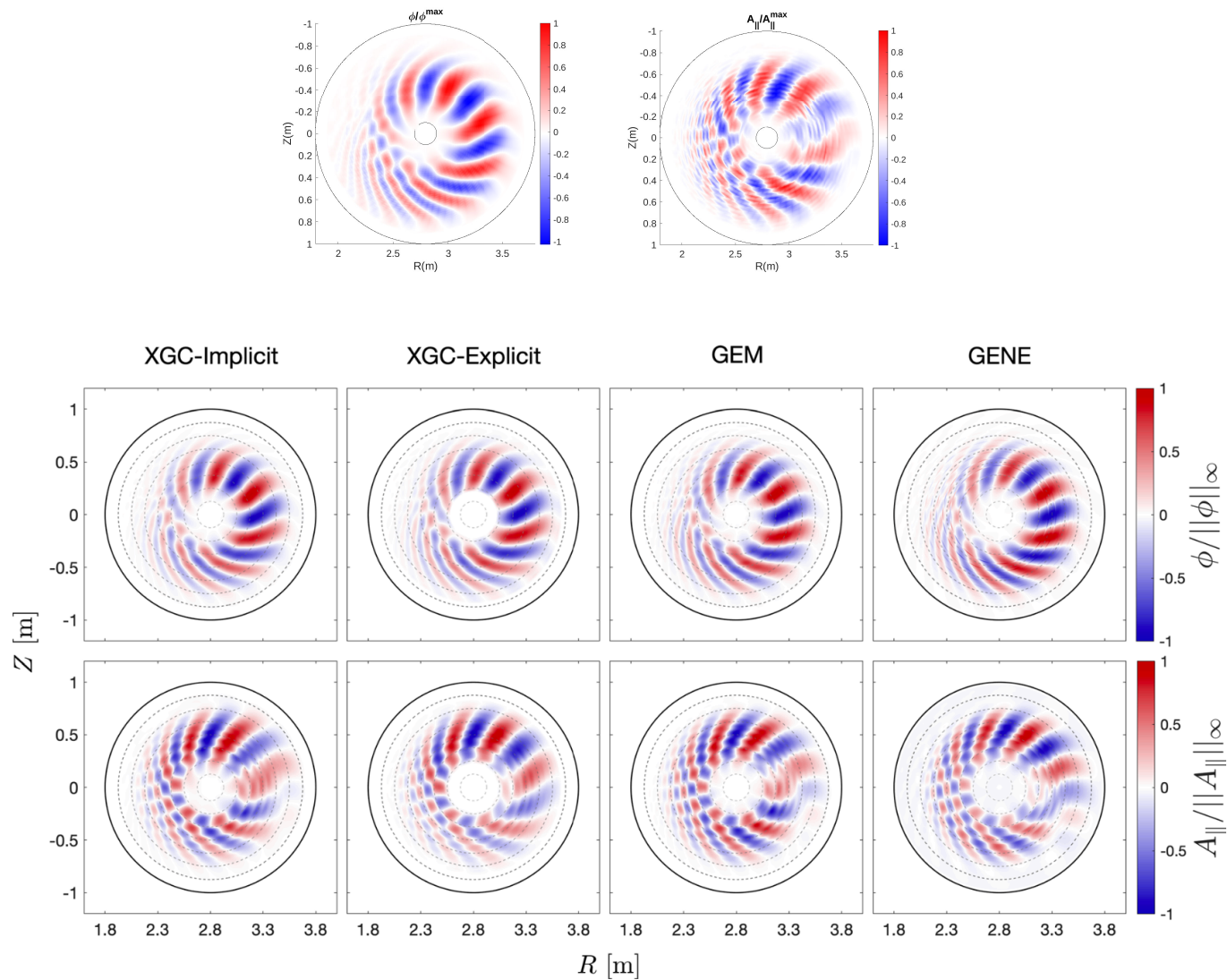
- Cyclone base case (CBC) hydrogen plasma with $a/\rho_i = 50$, $R/L_n = 2.22$, $R/L_{Ti} = R/L_{Te} = 6.92$.



[1] "Verification of a fully implicit particle-in-cell method for the v_{\parallel} -formalism of electromagnetic gyrokinetics in the XGC code", B. J. Sturdevant, Physics of Plasmas **28**, 072505 (2021).

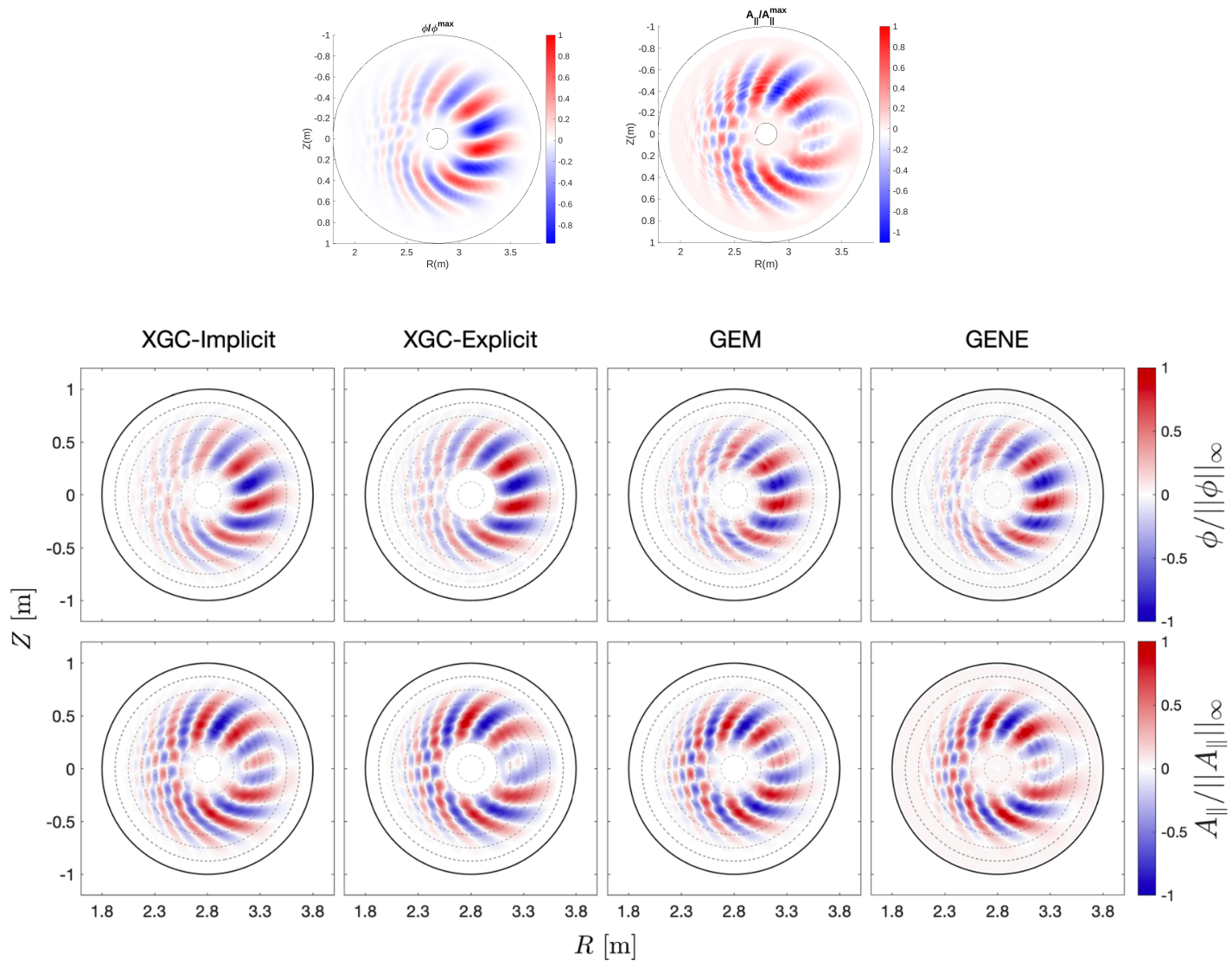
ITG mode, $\beta_e = 0.001$

- Comparison of GTS results with results of XGC, GEM and GENE.



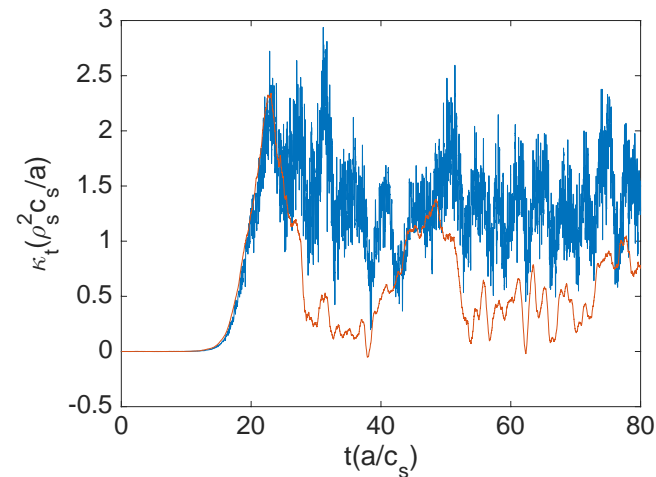
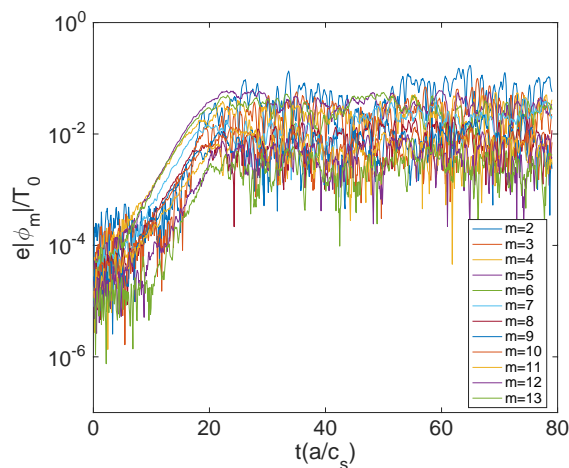
KBM mode, $\beta_e = 0.025$

- Comparison of GTS results with results of XGC, GEM and GENE.



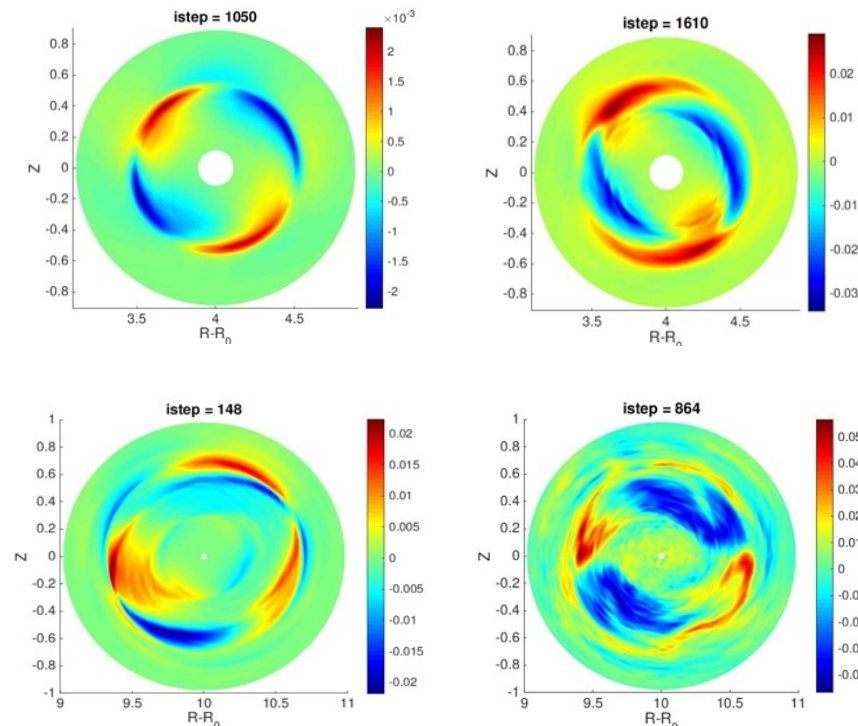
Nonlinear simulations of CBC case with $a/\rho_i = 50$ and $\beta_e = 0.03$

- Above threshold for KBM instability at $\beta_e = 0.013$.
- Heat flux is mostly in electron channel due to parallel transport along fluctuating magnetic field.
- Fluxes are 5x higher compared to $\beta_e = 0.005$ CBC case.
- Fluxes oscillate due to periodic recovery of the linear mode structure which can be a sign of predator-pray dynamics.



Nonlinear simulation of (2,1) tearing and double-tearing

- Possibility to study NTM since trapped particles are included.
- (2,1) –double tearing mode responsible for anomalous current penetration during fast current ramp-up.
- May explain internal disruptions in cases with $q \lesssim 1$.
- Maybe responsible for ITB in advanced tokamaks with negative shear.



Conclusion and Future work

- We have presented the implementation of EM pull-back scheme in GTS code.
- Numerous benchmarks against the eigenmode code and published results showcase the new capabilities of the code to simulate wide range of EM phenomena relevant to modern tokamaks.
- We also presented the nonlinear simulations of the kinetic ballooning instability in a model Cyclone plasma showing that KBM turbulence can be robustly simulated with δf gyrokinetic codes.
- Finally, we have also shown that the code is now capable of simulating non-linear, low- n , reduced MHD (low-beta) physics relevant for thermal quench. That includes kink and tearing modes which are considered as one of the major MHD perturbations that may lead to tokamak disruption.
- This new capability represents a major advance in studying these instabilities which up to now has been exclusively studied using fluid MHD codes with ad-hoc models for plasma resistivity and heat conductivity invalid for the hot and highly anisotropic fusion plasmas.
- On the hand our EM-GTS simulations can be considered as the first-principial simulation approach to studying these instabilities with all kinetic effects properly included.

Drift-Tearing Mode scaling

- For cylindrical plasma, drift-tearing mode scaling are

$$\frac{\delta_c}{\rho_i} \sim \frac{a\Delta'}{\beta(m_i/m_e)\rho_*},$$

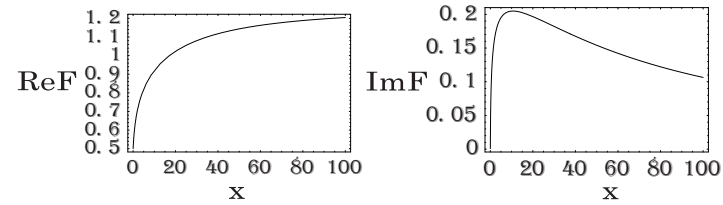
$$\frac{\gamma_c}{c_s/R} \sim n\rho_*^2 \frac{s(r_s\Delta')}{\beta\sqrt{m_i/m_e}} \left(\frac{a}{r_s}\right)^2,$$

$$\frac{\omega_*}{c_s/R} \sim m\rho_* \left(\frac{R}{L}\right) \left(\frac{a}{r_s}\right),$$

- where $s = d\ln q/d\ln r$, $\rho_* = \rho_i/a$, (n, m) are toroidal and poloidal mode numbers, and r_s is the location of the rational surface.
- For moderate β of several percent, $\delta_c/\rho_i \sim \rho_*$ and $\gamma_c/(c_s/R) \sim \rho_*^2$, which are quite small for $\rho_* \ll 1$.
- For the mode with $\nu \sim \omega_*$, the width of the current layer is

$$\frac{\delta}{\rho_i} \sim \delta_c \frac{\omega_*}{\gamma_c} \sim \left(\frac{q}{s}\right) \sqrt{\frac{m_e}{m_i}}.$$

Micro-tearing Mode Properties, cont'd



- If $\omega_{Te}^* \neq 0$ the mode is unstable. For example for $\omega_n^* = 0$

$$\frac{\omega}{\omega_{Te}^*} = F\left(\frac{\bar{\nu}}{\omega_{Te}^*}\right).$$

- Function $F(x)$ is plotted below for Maxwellian plasma and $\nu(v) = \bar{\nu}(v_{te}/v)^3$
- For given ω_{Te}^* the growth rate is maximized $Im\omega \approx 0.2\omega_{Te}^*$ for $5 < \bar{\nu}/\omega_{Te}^* < 20$.
- For given ω_{Te}^* the the mode frequency $1/2 < Re\omega/\omega_{Te}^* < 5/4$.

Micro-tearing Mode Properties, cont'd

- The role of neglected $\gamma_c/(c_s/R) \sim -m^2\rho_*^2/\beta$ (for $m \gg 1$) is to provide stabilization of the mode with sufficiently large m .
- Therefore the most unstable mode scales as

$$m \sim \frac{\beta}{\rho_*} \sqrt{\frac{m_i}{m_e}}, \quad \text{or,} \quad k_\theta \rho_i \sim \beta \sqrt{\frac{m_i}{m_e}},$$

- Provided that $\bar{\nu}/(c_s/R) \sim \omega_{Te}^*/(c_s/R) \sim m\rho_*(R/L_{Te})$.
- Localized micro-tearing mode can exist only if $\omega \sim \omega_{Te}^* < \omega_A(\rho_i)$, or

$$\omega_{Te}^* < \rho_i \frac{d}{dr} \left(\frac{k_\parallel c_s}{\sqrt{\beta}} \right), \quad \text{or,} \quad \beta \left(\frac{R}{L_{Te}} \right)^2 < \left(\frac{s}{q} \right)^2 \quad (\text{Gladd, 1980.}).$$